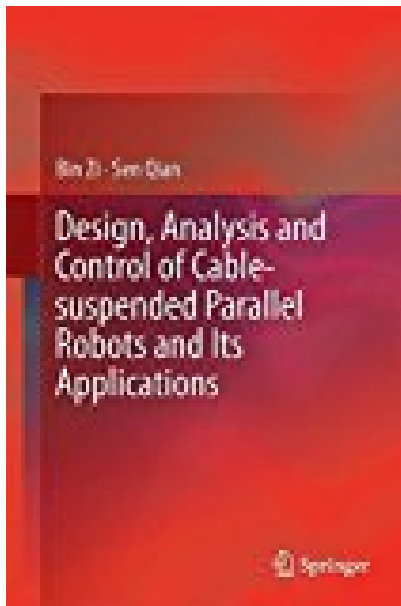


# Design Analysis and Control of Cable-suspended Parallel Robots and Its Applications

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## BOOK DETAILS

- Author : Bin Zi
- Pages : 301 Pages
- Publisher : Springer
- Language : English
- ISBN : 9811017522

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